

Human Machine Teaming (HMT) References

- [1] The Defense Science Board Report on Technology and Innovation Enablers for Superiority in 2030, October 2013.
- [2] Lee, J. D. “Trust, Trustworthiness, and Trustability,” Presented at the Workshop on Human Machine Trust for Robust Autonomous Systems, Ocala, FL, January–February 2012.
- [3] Stone M., “Brief on Autonomy Initiatives in the US DoD,” Autonomy Priority Steering Council, November 2012.
- [4] Overholt J. and Kerns K. “AFRL Human-Machine Teaming Strategic Vector,” AHEAD Membership Meeting, October 2014.
- [5] The Physic Hypertextbook, © 1998-2015 Glen Elert, <http://physics.info/machines/>
- [6] Landau, I. D., Lozano, R., Apos, M., Saad, M., and Karimi, A., “Adaptive Control Algorithms, Analysis and Applications,” Springer online at <http://www.springer.com/978-0-85729-663-4>, 2011.
- [7] Mac Schwager, “Towards Verifiable Adaptive Control for Safety Critical Applications,” Thesis, Department of Mechanical Engineering, Massachusetts Institute of Technology, June 2005.
- [8] Narendra, K. S., and Annaswamy, A. M. “Stable Adaptive Systems.” Prentice Hall, Englewood Cliff, New Jersey, 1989.
- [9] Slotine, J.J. E., and Li. W. “Applied Nonlinear Control,” Prentice Hall, Upper Saddle River, New Jersey, 1991.
- [10] Karason, S. P. and Annaswamy, A. M., “Adaptive Control in the Presence of Input Constraints,” IEEE Transactions on Automatic Control, vol. 39 pp. 2325-2330, Nov 1994.
- [11] Y. Santiago-Espada, R. R. Myer, K. A. Latorella and J. R. Comstock, Jr., “The Multi-Attribute Task Battery II (MATB-II) Software for Human Performance and Workload Research: A User’s Guide,” NASA/TM–2011-217164, July 2011.
- [12] Mark B. Abelson, MD, CM, FRCSC, and the ORA staff, Andover, Mass, “It’s Time to Think about the Blink,” *Review of Ophthalmology*, June, 13, 2011.